Transducers and Their Decision Problems

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String-to-String Transductions

 $f: \Sigma^* \hookrightarrow \Sigma^*$

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Append a #

 $abbab \mapsto abbab \#$

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 $abbab \mapsto abbab \#$ $abbab \mapsto aa$ $0100101 \mapsto 10100101$ $antwerp \mapsto prewtna$ $yes \mapsto yesyes$

Transductions are defined by Transducers





$aabaa \mapsto aaaa$









Parity bit

$01101\mapsto \boldsymbol{1}01101, 01111\mapsto \boldsymbol{0}011111$



Parity bit

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Parity bit





Non-determinism and relations

In general, transducers define binary relations in $\Sigma^* \times \Sigma^*$



defines $\{(u, v) \mid v \text{ is a subword of } u\}$

Formal Definition

Definition

A (finite state) transducer is a tuple $T = (\Sigma, Q, I, F, \Delta)$ where:

- \blacktriangleright Σ is a finite alphabet
- \blacktriangleright Q is a finite set of states
- $\blacktriangleright \ I \subseteq Q$ are the initial states and $F \subseteq Q$ are the final states
- $\Delta \subseteq Q \times \Sigma \times \Sigma^* \times Q$ is the transition relation.

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Semantics

A run is a sequence of transitions

$$r = q_0 \xrightarrow{\sigma_1: v_1} q_1 \dots q_{n-1} \xrightarrow{\sigma_n: v_n} q_n \qquad \sigma_i \in \Sigma$$

Its input is $in(r) = \sigma_1 \dots \sigma_n$ and its output $out(r) = v_1 \dots v_n$. The (rational) relation defined by T is:

 $[\![T]\!] = \{(in(r), \underbrace{out}(r)) \mid r \text{ is an accepting run}\}$

Application: Natural Language Processing

Natural Language Processing

Table of nouns and their plural forms

Noun singular	Noun plural
cat	cats
\log	dogs
cow	cows
fox	foxes
bus	buses
quiz	quizzes
goose	geese
$_{\mathrm{spy}}$	spies
city	cities

Natural Language Processing

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Natural Language Processing

Lexicon + spelling rules: Transducer for plural forms





Properties of Transducers

▶ Union

\blacktriangleright Union \checkmark

▶ Intersection

Closure Properties: Intersection

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3. are rational relations closed under intersection ? why ?

$$\bigcap := \left\{ \left(a^{n} l^{m}, a^{n} \right) \mid n = m > 0 \right\}$$

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- Composition : $R_2 \circ R_1 = \{(u, w) \mid \exists (u, v) \in R_1, (v, w) \in R_2\}.$

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Transducer vs Automata



Transducer vs Automata



Consider r_1, r_2 two runs on a^3 . We have $(in(r_1), out(r_1)) = (in(r_2), out(r_2))$ but different in-out words:

 $(a, \mathbf{a})(a, \mathbf{a})(a, \varepsilon) \neq (a, \varepsilon)(a, \mathbf{a})(a, \mathbf{a})$

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- ▶ Transducers are *asynchronous*
- Make most transducer problems conceptually difficult (and even computationally).

\Box = white space



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$\square aa \square a \square b \square aa \square a$

\Box = white space



$\square aa \square a \square \mapsto \square aa \square a$

Is non-determinism needed ?

\Box = white space



 $\square aa \square a \square \mapsto \square aa \square a$



Is non-determinism needed ? No.

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Semantics

$$\llbracket T \rrbracket : \left\{ \begin{array}{l} a^n b \mapsto b^{n+1} \\ a^n c \mapsto c^{n+1} \end{array} \right.$$

functional but not determinizable

Different classes of transductions



Functionality

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Thm (Choffrut 77, Weber, Klemm 95). Determinizability is decidable in PTIME.

Another Fundamental Problem: Equivalence

Def Given two transducers T_1, T_2 , does $\llbracket T_1 \rrbracket = \llbracket T_2 \rrbracket$ hold?

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Case of functional transducers

- ▶ Equivalence reduces to functionality:
 - **1.** test whether $dom(T_1) = dom(T_2)$
 - **2.** test whether $T_1 \uplus T_2$ is functional.

PSPACE PTIME

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General case

- ▶ Undecidable (Griffith 68),
- even if one alphabet is unary (Ibarra 78)

Summary – Transducers

Expressiveness:



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Equivalence: $(dom(T_1) = dom(T_2)$ is known)

input-deterministic	functional	non-deterministic
PTime	PTime	undec